# A matrix problem and a geometry problem 

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## Theorem (L. Molnár and W. Timmermann, 2011)

Let $\mathcal{H}$ be a complex separable Hilbert space with $\operatorname{dim} \mathcal{H} \geq 3$. Assume $\phi: \mathcal{B}_{s}(\mathcal{H}) \rightarrow \mathcal{B}_{s}(\mathcal{H})$ is a bijection such that

$$
\|[\phi(A), \phi(B)]\|=\|[A, B]\| \quad\left(A, B \in \mathcal{B}_{s}(\mathcal{H})\right)
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Then there exist either a unitary or an antiunitary operator $U$ on $\mathcal{H}$ and a function $f: \mathcal{B}_{s}(\mathcal{H}) \rightarrow \mathbb{R}$ such that

$$
\phi(A)= \pm U A U^{*}+f(A) I \quad\left(A \in \mathcal{B}_{s}(\mathcal{H})\right) .
$$

The proof uses the following theorem:

## Theorem (L. Molnár and P. Šemrl, 2005)

Let $\mathcal{H}$ be a complex separable Hilbert space with $\operatorname{dim} \mathcal{H} \geq 3$ and let $\phi: \mathcal{B}_{s}(\mathcal{H}) \rightarrow \mathcal{B}_{s}(\mathcal{H})$ be a bijective transformation which preserves commutativity in both directions.

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## Question

What happens in two dimensions?

## Commutativity preservers on $\mathcal{B}_{s}\left(\mathbb{C}^{2}\right)$

Two linearly independent operators $A, B \in \mathcal{B}_{s}\left(\mathbb{C}^{2}\right)$ commute
 $\exists \alpha, \beta \in \mathbb{R}$ s.t. $\alpha A+\beta B=I$.

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E.g. if $\phi: \mathcal{B}_{s}\left(\mathbb{C}^{2}\right) \rightarrow \mathcal{B}_{s}\left(\mathbb{C}^{2}\right)$ is non-singular and linear, then $\phi$ preserves commutativity in both directions
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So the preservation of commutativity provides too few information.

## The first step: linear commutativity preservers

## Theorem (with G. Nagy, 2014)

Suppose that $d \in \mathbb{N},\| \| \cdot \| \mid$ is an arbitrary unitarily invariant norm and $\phi: \mathcal{B}_{s}\left(\mathbb{C}^{d}\right) \rightarrow \mathcal{B}_{s}\left(\mathbb{C}^{d}\right)$ is a (real-)linear transformation such that

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\phi(A)=U A U^{*}+f(A) I \quad\left(A \in \mathcal{B}_{s}\left(\mathbb{C}^{d}\right)\right)
$$

or

$$
\phi(A)=-U A U^{*}+f(A) I \quad\left(A \in \mathcal{B}_{s}\left(\mathbb{C}^{d}\right)\right)
$$

## What can we do in general?

Problem (Reformulation)
Characterize those maps $\phi: \mathcal{B}_{s}\left(\mathbb{C}^{2}\right) \rightarrow \mathcal{B}_{s}\left(\mathbb{C}^{2}\right)$ s.t.

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\operatorname{det}[A, B]=\operatorname{det}[\phi(A), \phi(B)] \quad\left(A, B \in \mathcal{B}_{s}\left(\mathbb{C}^{2}\right)\right)
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Let $Z_{2}:=\left\{A \in \mathcal{B}_{s}\left(\mathbb{C}^{2}\right): \operatorname{Tr} A=0\right\}$ and

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\tilde{\phi}: \mathcal{B}_{s}\left(\mathbb{C}^{2}\right) \rightarrow Z_{2} \subseteq \mathcal{B}_{s}\left(\mathbb{C}^{2}\right), \quad \tilde{\phi}(A)=\phi(A)-\frac{\operatorname{Tr} \phi(A)}{2} \cdot I
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We can prove the following:

$$
\tilde{\phi}(A)= \pm \psi\left(A-\frac{\operatorname{Tr} A}{2} /\right) \quad\left(A \in \mathcal{B}_{s}\left(\mathbb{C}^{2}\right)\right)
$$

Now, we identify elements of $Z_{2}$ with vectors of $\mathbb{R}^{3}$ using the vector space isomorphism

$$
\iota: \mathbb{R}^{3} \rightarrow Z_{2}, \quad(a, b, c) \mapsto\left(\begin{array}{cc}
a & b+i c \\
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\end{array}\right)
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A rather simple calculation shows the following two equations:

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\operatorname{det}\left[\iota\left(a_{1}, b_{1}, c_{1}\right), \iota\left(a_{2}, b_{2}, c_{2}\right)\right]=4\left|\left(a_{1}, b_{1}, c_{1}\right) \times\left(a_{2}, b_{2}, c_{2}\right)\right|^{2}
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## Problem (Reformulation \#2)

Characterize those maps $\phi: \mathbb{R}^{3} \rightarrow \mathbb{R}^{3}$ s.t.

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\forall(\vec{a}, \vec{b})=(\phi(\vec{a}), \phi(\vec{b})) \quad\left(\forall \vec{a}, \vec{b} \in \mathbb{R}^{3}\right)
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where $(\vec{a}, \vec{b})=|\vec{a} \times \vec{b}|=$

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Of course, the similar question could be asked for an arbitrary real Hilbert space $E$. This is the Rassias-Wagner problem.

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(Beckmann-Quarles; Lester-Martin, linear R-W)

## Theorem (G.)

Let $E$ be a real (not necessarily separable) Hilbert space and $\phi: E \rightarrow E$ be an arbitrary transformation such that

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\begin{equation*}
(\vec{a}, \vec{b})=(\phi(\vec{a}), \phi(\vec{b})) \quad(\forall \vec{a}, \vec{b} \in E) \tag{1}
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(i) If $\operatorname{dim} E=2$, then there exists a linear operator $A: E \rightarrow E$ with $|\operatorname{det} A|=1$ such that the following holds:

$$
\begin{equation*}
\phi(\vec{a})= \pm A \vec{a} \quad(\vec{a} \in E) . \tag{2}
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$$

## Theorem (G. continued)

(ii) If $2<\operatorname{dim} E<\infty$, then there exists an orthogonal linear operator $R: E \rightarrow E$ such that

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is satisfied.

## Theorem (G. continued)

(ii) If $2<\operatorname{dim} E<\infty$, then there exists an orthogonal linear operator $R: E \rightarrow E$ such that

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is satisfied.
(iii) If $\operatorname{dim} E=\infty$ and in addition $\phi$ is assumed to be bijective, then there exists a linear, surjective isometry $R: E \rightarrow E$ such that we have

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## Outline of the proof for $n=3$

Let us consider the projectivised $\mathbb{R}^{3}$ which will be denoted by $\mathcal{P}\left(\mathbb{R}^{3}\right)$. The subspace generated by $\vec{v}$ will be denoted by [ $\left.\vec{v}\right]$. Let

$$
g_{\phi}: \mathcal{P}\left(\mathbb{R}^{3}\right) \rightarrow \mathcal{P}\left(\mathbb{R}^{3}\right), \quad g_{\phi}([\vec{v}])=[\phi(\vec{v})](\vec{v} \neq \overrightarrow{0})
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Note that $\phi(\vec{v})=\overrightarrow{0} \Longleftrightarrow \vec{v}=\overrightarrow{0}$.

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Note that $\phi(\vec{v})=\overrightarrow{0} \Longleftrightarrow \vec{v}=\overrightarrow{0}$.
STEP 1: We prove that $g_{\phi}$ is a homeomorphism.

STEP 2: We consider two linearly independent vectors $\vec{a}, \vec{b} \in E$ and let

$$
C_{\vec{a}, \vec{b}}:=\{\vec{v} \in E \backslash\{0\}:(\vec{v}, \vec{a})=(\vec{v}, \vec{b})\} \subseteq E
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(note that $C_{\vec{a}, \vec{b}}$ is a plane iff $|\vec{a}|=|\vec{b}|$ )

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We can show that $P C_{\vec{a}, \vec{b}}$ contains a loop $\gamma:[0,1] \rightarrow P C_{\vec{a}, \vec{b}}$ not homotopic to the trivial loop $\delta:[0,1] \rightarrow P C_{\vec{a}, \vec{b}}, \delta \equiv \gamma(0)$ if and only if $|\vec{a}|=|\vec{b}|$ holds.

STEP 3: Using that $g_{\phi}$ is a homeomorphism, we obtain that

$$
|\phi(\vec{a})|=\lambda_{\phi}|\vec{a}| \quad\left(\vec{a} \in \mathbb{R}^{3}\right)
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holds with some $\lambda_{\phi}>0$.

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we obtain

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|\langle\vec{a}, \vec{b}\rangle|=|\langle\phi(\vec{a}), \phi(\vec{b})\rangle| \quad\left(\vec{a}, \vec{b} \in \mathbb{R}^{3}\right)
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$$

Finally, we apply Wigner's theorem.

## Back to the Molnár-Timmermann problem

## Theorem (G.)

Fix a unitarily invariant norm $\left\|\|\cdot\| \mid\right.$ on $\mathbb{C}^{d \times d}$ where $d \geq 2$. Let $\phi: \mathcal{B}_{s}\left(\mathbb{C}^{d}\right) \rightarrow \mathcal{B}_{s}\left(\mathbb{C}^{d}\right)$ be an arbitrary transformation for which the following holds:

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\begin{equation*}
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is satisfied.

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Let $\mathcal{H}$ be a separable Hilbert space and fix a unitarily invariant norm ||| $\left|\left|\mid\right.\right.$ on $\mathcal{B}(\mathcal{H})$. Let $\phi: \mathcal{B}_{s}(\mathcal{H}) \rightarrow \mathcal{B}_{s}(\mathcal{H})$ be a bijection for which the following holds:

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\|\|[A, B]\|\|=\|[\phi(A), \phi(B)]\| \| \quad\left(A, B \in H_{d}\right)
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## Back to the Molnár-Timmermann problem (cont.)

## Theorem (G.)

Let $\mathcal{H}$ be a separable Hilbert space and fix a unitarily invariant norm ||| ||| on $\mathcal{B}(\mathcal{H})$. Let $\phi: \mathcal{B}_{s}(\mathcal{H}) \rightarrow \mathcal{B}_{s}(\mathcal{H})$ be a bijection for which the following holds:

$$
\|\|[A, B]\|\|=\| \|[\phi(A), \phi(B)]\| \| \quad\left(A, B \in H_{d}\right)
$$

Then there exist a function $f: \mathcal{B}_{s}(\mathcal{H}) \rightarrow \mathbb{R}$ and a unitary or antiunitary operator $U$ such that

$$
\phi(A)= \pm U A U^{*}+f(A) I \quad\left(A \in \mathcal{B}_{s}(\mathcal{H})\right)
$$

is satisfied.

## k-parallelepipeds

For any $k$ vectors $\vec{a}_{1}, \ldots \vec{a}_{k} \in E$ let us denote the $k$-dimensional volume of the parallelepiped spanned by them by the symbol $\rangle_{k}\left(\vec{a}_{1}, \ldots \vec{a}_{k}\right)$.

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## Theorem (G.)

Let $E$ be a real (not necessarily separable) Hilbert space, $2<k<\infty, k \leq \operatorname{dim} E$ and $\phi: E \rightarrow E$ be a transformation such that

$$
\begin{equation*}
\boldsymbol{v}_{k}\left(\vec{a}_{1}, \ldots \vec{a}_{k}\right)=\left(\phi\left(\vec{a}_{1}\right), \ldots \phi\left(\vec{a}_{k}\right)\right) \quad\left(\forall \vec{a}_{1}, \ldots \vec{a}_{k} \in E\right) . \tag{5}
\end{equation*}
$$

## Theorem (G., cont.)

(i) If $\operatorname{dim} E=k$, then there exists a linear operator $A: E \rightarrow E$ with $|\operatorname{det} A|=1$ such that the following holds:

$$
\begin{equation*}
\phi(\vec{a})= \pm A \vec{a} \quad(\vec{a} \in E) . \tag{6}
\end{equation*}
$$

## Theorem (G., cont.)

(i) If $\operatorname{dim} E=k$, then there exists a linear operator $A: E \rightarrow E$ with $|\operatorname{det} A|=1$ such that the following holds:

$$
\begin{equation*}
\phi(\vec{a})= \pm A \vec{a} \quad(\vec{a} \in E) . \tag{6}
\end{equation*}
$$

(ii) If $2<k<\operatorname{dim} E(\leq \infty)$, then there exists a linear (not necessarily surjective) isometry $R: E \rightarrow E$ such that

$$
\phi(\vec{a})= \pm R \vec{a} \quad(\vec{a} \in E)
$$

is satisfied.

The proof is a straightforward consequence of the fundamental theorem of projective geometry.

## Back to the parallelogram case

Note that if we knew that $[\vec{c}] \subseteq[\vec{a}, \vec{b}]$, then we could use the fundamental theorem of projective geometry and drop the bijectivity condition.

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## Question

If $\operatorname{dim} E=\infty$, is the condition

$$
[\vec{c}] \subseteq[\vec{a}, \vec{b}] \Longrightarrow[\phi(\vec{c})] \subseteq[\phi(\vec{a}), \phi(\vec{b})]
$$

satisfied?

## Back to the parallelogram case

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## Question

If $\operatorname{dim} E=\infty$, is the condition

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## satisfied?

## Problem

Let $E$ be an arbitrary real Hilbert space. Characterize those transformations $\phi: \mathbb{R}^{2} \rightarrow E$ which preservers the area of parallelograms.

## Problem

Describe those transformations $\phi: E \rightarrow E$ s. $t$.

$$
\diamond(\vec{a}, \vec{b})=1 \Longrightarrow(\phi(\vec{a}), \phi(\vec{b}))=1
$$

holds.

## Problem

Describe those transformations $\phi: E \rightarrow E$ s. $t$.

$$
\diamond(\vec{a}, \vec{b})=1 \Longrightarrow(\phi(\vec{a}), \phi(\vec{b}))=1
$$

holds.

## Problem

Characterize those transformations $\phi: E \rightarrow E$ s. $t$.

$$
\checkmark(\vec{a}, \vec{b})=0 \Longrightarrow(\phi(\vec{a}), \phi(\vec{b}))=0
$$

and

$$
\diamond(\vec{a}, \vec{b})=1 \Longrightarrow(\phi(\vec{a}), \phi(\vec{b}))=1
$$

are satisfied.

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## Thank You for Your Kind Attention

