

Pythagorean-hodograph curves

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Let $\mathbf{r} : [a, b] \rightarrow \mathbb{R}^2$ be a **planar polynomial parametric curve**

$$\mathbf{r}(t) = \begin{pmatrix} x(t) \\ y(t) \end{pmatrix},$$

where

$$x(t) = \sum_{k=0}^n a_k t^k \quad \text{and} \quad y(t) = \sum_{k=0}^n b_k t^k$$

are polynomials of degree $\leq n$.

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Curve \mathbf{r} is a **Pythagorean-hodograph** curve, if there exists a **polynomial** σ , such that

$$x'(t)^2 + y'(t)^2 = \sigma(t)^2.$$

Such a curve will be (shortly) called a **PH curve**.

PH curves have several **important properties**:

- If a curve is a **regular** one (the derivative never vanishes), then

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- Their **arc length**

$$\int_a^b \|r'(t)\| dt = \int_a^b \sigma(t) dt$$

can be computed **exactly** (without quadrature rules).

- Unit tangent \mathbf{t} is a rational curve

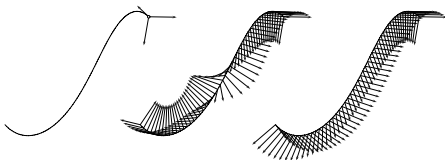
$$\mathbf{t}(t) = \frac{(x'(t), y'(t))}{\sigma(t)}.$$

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Application:

- Any orthonormal adapted frame (first vector is a unit tangent) of a spatial curve may define the motion of a rigid body.
- It is important to have a rational rotation minimizing frame.
- To have a rational unit tangent, the curve must be a PH curve.



- Their **offset curves**

$$\mathbf{r}_d(t) := \mathbf{r}(t) + d \mathbf{n}(t),$$

where $d > 0$ and $\mathbf{n}(t)$ is a **unit normal** to \mathbf{r} at parameter t ,

$$\mathbf{n}(t) := \frac{(-y'(t), x'(t))}{\sqrt{x'(t)^2 + y'(t)^2}},$$

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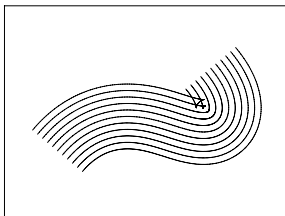
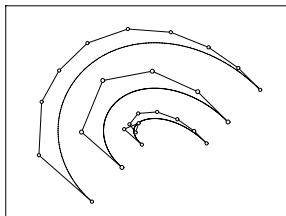
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are **rational curves**.

- If the degree of \mathbf{r} is n , then the degree of \mathbf{r}_d is $2n - 1$.



Theorem (Kubota)

The Pythagorean condition

$$a^2(t) + b^2(t) = c^2(t)$$

is satisfied by polynomials a , b and c iff there *exist* polynomials u , v and w , such that

$$a(t) = w(t) (u^2(t) - v^2(t)),$$

$$b(t) = 2 w(t) u(t) v(t),$$

$$c(t) = w(t) (u^2(t) + v^2(t)),$$

where u and v are *relatively prime*.

From the theorem it follows that the **hodograph** of a PH curve has to be of the form

$$\begin{aligned}x'(t) &= w(t) (u^2(t) - v^2(t)), \\y'(t) &= 2 w(t) u(t) v(t).\end{aligned}$$

(the order is not important, since PH curves are **rotational invariant**).

We will now **eliminate** some **uninteresting** cases:

- $w = 0$ or $u = v = 0$; PH curve \mathbf{r} is a **point**,

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- u and v are nonzero constants, w is not a constant; PH curve is **nonuniformly parameterized straight line**.
- $w \neq 0$ and $u = \pm v$ or at least one of u, v equals zero; PH curve is **nonuniformly parameterized straight line**.

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- u and v are **nonzero constants**, w is **not a constant**; PH curve is **nonuniformly parameterized straight line**.
- $w \neq 0$ and $u = \pm v$ or at least one of u, v equals zero; PH curve is **nonuniformly parameterized straight line**.

Therefore, we will only consider cases, where $u, v, w \neq 0$, and u, v **not both constants**.

Such PH curves are of **degree** at least **3**.

PH curves have clearly less degrees of freedom than general polynomial curves

Lema

PH curve of degree n has (at most) $n + 3$ degrees of freedom ($n - 1$ less than general polynomial curve of degree n).

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Conjecture:

PH curve can **interpolate $n + 1$ points in the geometric sense.**

For **prescribed** parameters PH curve can interpolate at most $\lfloor (n + 3)/2 \rfloor$ points.

- First interesting case are **cubic** PH curves, where $w = 1$, $\max\{\deg(u), \deg(v)\} = 1$.
- **Non-constant** $w(t)$ may produce **irregular** curves, if w has real roots within the curve parameter domain. Therefore, we take $w(t) = 1$. Then the PH curve is always of **odd** degree.

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- Let us write u and v in the Bernstein-Bézier form

$$u(t) = u_0 B_0^1(t) + u_1 B_1^1(t),$$

$$v(t) = v_0 B_0^1(t) + v_1 B_1^1(t),$$

where

$$B_k^n(t) = \binom{n}{k} (1-t)^{n-k} t^k$$

and assume $u_0 : u_1 \neq v_0 : v_1$.

We obtain the cubic PH curve

$$\mathbf{r}(t) = (x(t), y(t))^T = \sum_{k=0}^3 \mathbf{p}_k B_k^n(t)$$

as

$$x(t) = \int_0^t (u^2(t) - v^2(t)) dt,$$

$$y(t) = \int_0^t 2 u(t) v(t) dt.$$

Theorem

Control points of a cubic Bézier PH curve satisfy

$$\mathbf{p}_1 = \mathbf{p}_0 + \frac{1}{3} (u_0^2 - v_0^2, 2 u_0 v_0)^T,$$

$$\mathbf{p}_2 = \mathbf{p}_1 + \frac{1}{3} (u_0 u_1 - v_0 v_1, u_0 v_1 + u_1 v_0)^T,$$

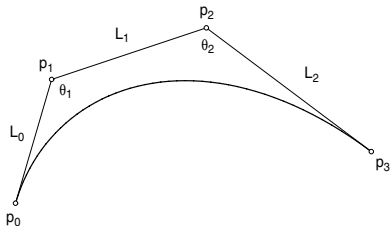
$$\mathbf{p}_3 = \mathbf{p}_2 + \frac{1}{3} (u_1^2 - v_1^2, 2 u_1 v_1)^T,$$

where \mathbf{p}_0 is an arbitrary control point, satisfying constants from integration.

Theorem (Characterization)

Let \mathbf{r} be a cubic Bézier curve with control points \mathbf{p}_k , $k = 0, \dots, 3$. Moreover let $L_i := \|\Delta \mathbf{p}_i\|$, $i = 0, 1, 2$ and let θ_1 and θ_2 be the control polygon angles at the interior vertices \mathbf{p}_1 and \mathbf{p}_2 . Then \mathbf{r} is a **PH curve** iff

$$L_1 = \sqrt{L_0 L_2} \quad \text{and} \quad \theta_1 = \theta_2.$$



Planar PH curves are connected with complex numbers.

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Let us identify

$$(x, y)^T \in \mathbb{R}^2 \rightarrow x + \mathbf{i}y.$$

Planar curve \mathbf{r} therefore becomes

$$\mathbf{r}(t) = (x(t), y(t))^T \rightarrow \mathbf{z}(t) := x(t) + \mathbf{i}y(t).$$

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Notation:

- Π ... regular polynomial curves in \mathbb{R}^2 ,
- $\hat{\Pi}$... regular PH curves in \mathbb{R}^2 .

- Clearly

$$\hat{\Pi} \subset \Pi,$$

since there **exist regular curves**, which are **not PH curves**, e.g.,

$$\mathbf{z}(t) = t + i t^2.$$

- Let us define the mapping $\mathcal{P} : \mathbf{z}(t) \rightarrow \hat{\mathbf{z}}(t)$ as:
 - $\mathbf{w}(t) := \mathbf{z}'(t),$

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- Let us define the mapping $\mathcal{P} : \mathbf{z}(t) \rightarrow \hat{\mathbf{z}}(t)$ as:

- $\mathbf{w}(t) := \mathbf{z}'(t),$
- $\hat{\mathbf{w}}(t) := \mathbf{w}^2(t),$
- $\hat{\mathbf{z}}(t) := \int \hat{\mathbf{w}}(\tau) d\tau.$

Here we assume $\mathbf{z}(0) = \hat{\mathbf{z}}(0) = 0.$

Theorem

Mapping \mathcal{P} is a *bijection* from Π to $\widehat{\Pi}$.

Remark: Sets Π and $\widehat{\Pi}$ have the same cardinality.

Lemma:

If n is the degree of \mathbf{z} and \widehat{n} is the degree of $\widehat{\mathbf{z}}$, then

$$\widehat{n} = 2n - 1.$$

Corollary:

There are *no regular PH curves of even degree*.

Let $\mathbf{r} : [a, b] \rightarrow \mathbb{R}^3$ be a **spatial polynomial parametric curve**

$$\mathbf{r}(t) = \begin{pmatrix} x(t) \\ y(t) \\ z(t) \end{pmatrix}.$$

Curve \mathbf{r} is a spatial **Pythagorean-hodograph** curve, if there exists a **polynomial** σ , such that

$$x'(t)^2 + y'(t)^2 + z'(t)^2 = \sigma(t)^2.$$

Theorem (Kubota)

The Pythagorean condition

$$a^2(t) + b^2(t) + c^2(t) = d^2(t)$$

is satisfied by relatively prime polynomials a , b , c and d iff there exist polynomials u , v , p and q , such that

$$a(t) = u^2(t) + v^2(t) - p^2(t) - q^2(t),$$

$$b(t) = 2[u(t)q(t) + v(t)p(t)],$$

$$c(t) = 2[v(t)q(t) - u(t)p(t)],$$

$$d(t) = u^2(t) + v^2(t) + p^2(t) + q^2(t).$$

From the theorem it follows that the **hodograph** of a spatial PH curve has to be of the form

$$x'(t) = u^2(t) + v^2(t) - p^2(t) - q^2(t),$$

$$y'(t) = 2[u(t)q(t) + v(t)p(t)],$$

$$z'(t) = 2[v(t)q(t) - u(t)p(t)].$$

From the theorem it follows that the **hodograph** of a spatial PH curve has to be of the form

$$\begin{aligned}x'(t) &= u^2(t) + v^2(t) - p^2(t) - q^2(t), \\y'(t) &= 2[u(t)q(t) + v(t)p(t)], \\z'(t) &= 2[v(t)q(t) - u(t)p(t)].\end{aligned}$$

If the polynomials u, v, p, q are of degree n , then the PH curve is of degree $2n + 1$.

Spatial PH curves are connected with quaternions.

Spatial PH curves are connected with **quaternions**.

Quaternions:

- They form a 4-dimensional vector space \mathbb{H} with standard basis $\{\mathbf{1}, \mathbf{i}, \mathbf{j}, \mathbf{k}\}$,

$$\mathbf{1} = (1, 0, 0, 0), \quad \mathbf{i} = (0, 1, 0, 0), \quad \mathbf{j} = (0, 0, 1, 0), \quad \mathbf{k} = (0, 0, 0, 1).$$

- First component is a **scalar part**, other three components form a **vector part**.
- Let $\mathcal{A} = (a, \mathbf{a})$ and $\mathcal{B} = (b, \mathbf{b})$, $a, b \in \mathbb{R}$, $\mathbf{a}, \mathbf{b} \in \mathbb{R}^3$, then

$$\mathcal{A} + \mathcal{B} = (a + b, \mathbf{a} + \mathbf{b}), \quad \mathcal{A}\mathcal{B} = (ab - \mathbf{a} \cdot \mathbf{b}, \mathbf{a}\mathbf{b} + \mathbf{b}\mathbf{a} - \mathbf{a} \times \mathbf{b}).$$

- $\mathcal{A}^* := (a, -\mathbf{a})$

- Let $\mathcal{A}(t) = u(t) + v(t)\mathbf{i} + p(t)\mathbf{j} + q(t)\mathbf{k} \in \mathbb{H}$.
- Then

$$\begin{aligned}\mathbf{r}'(t) &= \mathcal{A}(t)\mathbf{i}\mathcal{A}^*(t) \\ &= [u^2(t) + v^2(t) - p^2(t) - q^2(t)]\mathbf{i} \\ &\quad + 2[u(t)q(t) + v(t)p(t)]\mathbf{j} \\ &\quad + 2[v(t)q(t) - u(t)p(t)]\mathbf{k}.\end{aligned}$$

Procedure:

$$\mathbf{r}(t) := \int_0^t \mathcal{A}(t)\mathbf{i}\mathcal{A}^*(t) dt$$

Thank you!