# A characterization of Leonard pairs using the notion of a tail 

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## Introduction

This talk is about Leonard pairs and Leonard systems, which are defined using linear algebra.

Leonard pairs have applications to such areas as distance-regular graphs, orthogonal polynomials, and representation theory.

In this talk, we characterize the Leonard pairs using the notion of a tail. This notion was originally introduced in the context of distance-regular graphs.

The main theorem can be viewed as an algebraic version of a theorem of Jurišić, Terwilliger, and Zitnik proven for $Q$-polynomial distance-regular graphs in 2009.

## Preliminaries

We begin by establishing some preliminaries.

- Let $\mathbb{K}$ denote a field.
- Fix a vector space $V$ of dimension $d+1(d \geq 1)$.
- Let $\operatorname{Mat}_{d+1}(\mathbb{K})$ denote the $\mathbb{K}$-algebra of all $d+1$ by $d+1$ matrices with entries in $\mathbb{K}$.
- Let $\mathcal{A}=\operatorname{End}(V)$. Note that $\mathcal{A}$ is isomorphic to $\operatorname{Mat}_{d+1}(\mathbb{K})$.


## Tridiagonal matrices

- A square matrix is tridiagonal whenever each nonzero entry lies on either the diagonal, the subdiagonal, or the superdiagonal.
- A tridiagonal square matrix is irreducible whenever each entry on the subdiagonal is nonzero and each entry on the superdiagonal is nonzero.


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Example

$$
\left(\begin{array}{cccc}
2 & -1 & 0 & 0 \\
1 & 0 & 3 & 0 \\
0 & -7 & 4 & 2 \\
0 & 0 & 6 & -9
\end{array}\right) \text { and }\left(\begin{array}{cccc}
1 & 0 & 0 & 0 \\
2 & -1 & 3 & 0 \\
0 & 8 & 6 & 5 \\
0 & 0 & 0 & 9
\end{array}\right)
$$

The matrix on the left is irreducible tridiagonal, but the one on the right is not.

## Definition of a Leonard pair

## Definition

Let $V$ denote a vector space over $\mathbb{K}$ with finite positive dimension. By a Leonard pair on $V$, we mean an ordered pair of linear transformations $A: V \rightarrow V$ and $A^{*}: V \rightarrow V$ that satisfy the following properties:
(1) There exists a basis for $V$ with respect to which the matrix representing $A$ is irreducible tridiagonal and the matrix representing $A^{*}$ is diagonal.
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## Note

It is a common notational convention to use $A^{*}$ to represent the conjugate-transpose of $A$. We are not using this convention.

## Idempotents

When working with a Leonard pair, it is useful to consider a closely related object called a Leonard system. However, it is first necessary to establish the following definitions.

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## Definition

By a system of mutually orthogonal idempotents in $\mathcal{A}$, we mean a sequence $\left\{E_{i}\right\}_{i=0}^{d}$ of elements in $\mathcal{A}$ such that

$$
\begin{array}{cc}
E_{i} E_{j}=\delta_{i, j} E_{i} & (0 \leq i, j \leq d), \\
\operatorname{rank}\left(E_{i}\right)=1 & (0 \leq i \leq d) .
\end{array}
$$

## Decompositions

## Definition

By a decomposition of $V$, we mean a sequence $\left\{U_{i}\right\}_{i=0}^{d}$ consisting of one-dimensional subspaces of $V$ such that

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\left.V=\sum_{i=0}^{d} U_{i} \quad \quad \text { (direct sum }\right)
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Given a decomposition, the projections onto the components are mutually orthogonal idempotents. Conversely, a decomposition can be defined from a set of mutually orthogonal idempotents.

## Primitive idempotents

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Let $A$ denote a multiplicity-free element of $\mathcal{A}$ and let $\left\{\theta_{i}\right\}_{i=0}^{d}$ denote an ordering of the eigenvalues of $A$. For $0 \leq i \leq d$, let $U_{i}$ denote the eigenspace of $A$ for $\theta_{i}$. Then $\left\{U_{i}\right\}_{i=0}^{d}$ is a decomposition of $V$; let $\left\{E_{i}\right\}_{i=0}^{d}$ denote the corresponding system of idempotents. We refer to $E_{i}$ as the primitive idempotent of $A$ corresponding to $U_{i}$ (or $\theta_{i}$ ).

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## Note

$A=\sum_{i=0}^{d} \theta_{i} E_{i}$ and $A E_{i}=E_{i} A=\theta_{i} E_{i}$ for $0 \leq i \leq d$.

## Leonard systems

## Definition

By a Leonard system on $V$, we mean a sequence

$$
\left(A ;\left\{E_{i}\right\}_{i=0}^{d} ; A^{*} ;\left\{E_{i}^{*}\right\}_{i=0}^{d}\right)
$$

which satisfies the following properties.
(1) Each of $A, A^{*}$ is a multiplicity-free element of $\mathcal{A}$.
(2) $\left\{E_{i}\right\}_{i=0}^{d}$ is an ordering of the primitive idempotents of $A$.
(3) $\left\{E_{i}^{*}\right\}_{i=0}^{d}$ is an ordering of the primitive idempotents of $A^{*}$.
(9) $E_{i}^{*} A E_{j}^{*}= \begin{cases}0, & \text { if }|i-j|>1 ; \\ \neq 0, & \text { if }|i-j|=1\end{cases}$

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## Leonard systems (continued)

## Note

A Leonard system gives rise to a Leonard pair and vice versa. Also, if $A, A^{*}$ are a Leonard pair, then $A$ and $A^{*}$ are multiplicity-free.

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E_{i}^{*} A E_{j}^{*}=\left\{\begin{array}{ll}
0, & \text { if }|i-j|>1 ; \\
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\end{array} \quad(0 \leq i, j \leq d)\right.
$$

Let $\left\{\theta_{i}^{*}\right\}_{i=0}^{d}$ denote scalars in $\mathbb{K}$ and let $A^{*}=\sum_{i=0}^{d} \theta_{i}^{*} E_{i}^{*}$. To avoid trivialities, assume that $d \geq 1$.

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Let $\left\{\theta_{i}^{*}\right\}_{i=0}^{d}$ denote scalars in $\mathbb{K}$ and let $A^{*}=\sum_{i=0}^{d} \theta_{i}^{*} E_{i}^{*}$. To avoid trivialities, assume that $d \geq 1$.

## Facts

- $E_{0}^{*}, A$ generate $\mathcal{A}$.
- There exists an antiautomorphism $\dagger$ of $\mathcal{A}$ that fixes $E_{i}, A^{*}$.


## The graph $\Delta$

We will now examine a set of conditions necessary to guarantee that $\left(A ;\left\{E_{i}\right\}_{i=0}^{d} ; A^{*} ;\left\{E_{i}^{*}\right\}_{i=0}^{d}\right)$ is a Leonard system. To do so, we first define a graph $\Delta$.

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## Definition

Let $\Delta$ be the graph with vertex set $\{0,1, \ldots, d\}$ such that two vertices $i$ and $j$ are adjacent if and only if $i \neq j$ and $E_{i} A^{*} E_{j} \neq 0$.

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## Note

The graph $\Delta$ is finite and undirected, without loops or multiple edges. Also, $\Delta$ is well-defined because of the antiautomorphism $\dagger$.

## Leonard systems and $\Delta$

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## Lemma

The sequence $\left(A ;\left\{E_{i}\right\}_{i=0}^{d} ; A^{*} ;\left\{E_{i}^{*}\right\}_{i=0}^{d}\right)$ is a Leonard system if and only if the graph $\Delta$ is a path such that vertices $i-1, i$ are adjacent for $1 \leq i \leq d$.

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The "only if" statement and most of the details of the "if" statement follow from the definitions.

The bulk of the work in proving the "if" statement involves proving that $A^{*}$ is multiplicity-free. This is accomplished by showing that the minimal polynomial for $A^{*}$ has distinct roots and is degree $d+1$.

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The given ordering $\left\{E_{i}\right\}_{i=0}^{d}$ of the primitive idempotents of $A$ is said to be Q-polynomial whenever the equivalent conditions in the previous lemma hold.

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## Definition

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## Definition

Let $(E, F)$ denote an ordered pair of distinct primitive idempotents for $A$. This pair will be called Q-polynomial whenever there exists a $Q$-polynomial ordering $\left\{E_{i}\right\}_{i=0}^{d}$ of the primitive idempotents of $A$ such that $E=E_{0}$ and $F=E_{1}$.

## Tails

## Definition

Let $(E, F)=\left(E_{i}, E_{j}\right)$ denote an ordered pair of distinct primitive idempotents for $A$. This pair will be called a tail whenever the following occurs in $\Delta$ :
(1) $i$ is adjacent to no vertex in $\Delta$ besides $j$;
(3) $j$ is adjacent to at most one vertex in $\Delta$ besides $i$.

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## Lemma

Let $(E, F)$ denote an ordered pair of distinct primitive idempotents for $A$. If $(E, F)$ is $Q$-polynomial, then $(E, F)$ is a tail.

[^0]
## The main theorem

Theorem
Let $(E, F)$ denote an ordered pair of distinct primitive idempotents for $A$. Then this pair is Q-polynomial if and only if the following hold.
(1) $(E, F)$ is a tail.
(2) There exists $\beta \in \mathbb{K}$ such that $\theta_{i-1}^{*}-\beta \theta_{i}^{*}+\theta_{i+1}^{*}$ is independent of $i$ for $1 \leq i \leq d-1$.
(3) $\theta_{0}^{*} \neq \theta_{i}^{*}$ for $1 \leq i \leq d$.

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(3) $\theta_{0}^{*} \neq \theta_{i}^{*}$ for $1 \leq i \leq d$.

The "only if" statement follows mainly from the definitions, except for condition 2, which was shown by Terwilliger (2001).

The "if" statement can be proven by showing that conditions 1-3 imply that $\Delta$ is a path.

It is first necessary to show that $\Delta$ is connected.

## Proof outline part 2

Each connected component of $\Delta$ corresponds to a subspace of $V$ that is invariant under both $A$ and $A^{*}$. So, if $\Delta$ is not connected then there exists a subspace $U$ of $V$ such that $U \neq 0, U \neq V, A U \subseteq U$, and $A^{*} U \subseteq U$.

An important consequence of condition 3 is that both $A$ and $A^{*}$ generate $\mathcal{A}$. Therefore, $\mathcal{A} U \subseteq U$. Because $V$ is irreducible as an $\mathcal{A}$-module, either $U=0$ or $U=V$. This is a contradiction, so $\Delta$ is connected.

## Proof outline part 3

Assume without loss of generality that $E_{0}=E$ and $E_{1}=F$. Now $\Delta$ looks like:

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To show that $\Delta$ is a path, first let

$$
\gamma^{*}=\theta_{i-1}^{*}-\beta \theta_{i}^{*}+\theta_{i+1}^{*} \quad(1 \leq i \leq d-1)
$$

## Proof outline part 4

Using the three-term recurrence (condition 2), it can be shown that the expression

$$
\theta_{i-1}^{* 2}-\beta \theta_{i-1}^{*} \theta_{i}^{*}+\theta_{i}^{* 2}-\gamma^{*}\left(\theta_{i-1}^{*}+\theta_{i}^{*}\right)
$$

is independent of $i$ for $1 \leq i \leq d$. Call this expression $\delta^{*}$.

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is independent of $i$ for $1 \leq i \leq d$. Call this expression $\delta^{*}$.
Next, it follows that

$$
0=\left[A^{*}, A^{* 2} A-\beta A^{*} A A^{*}+A A^{* 2}-\gamma^{*}\left(A A^{*}+A^{*} A\right)-\delta^{*} A\right],
$$

where $[x, y]=x y-y x$.

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where $[x, y]=x y-y x$.
This can be proven using the following facts:

- $I=\sum_{i=0}^{d} E_{i}^{*}$,
- $E_{i}^{*} A^{*}=\theta_{i}^{*} E_{i}^{*}$, and
- $A^{*} E_{j}^{*}=\theta_{j}^{*} E_{j}^{*}$.


## Proof outline part 5

Suppose we are given vertices $i$ and $j$ in $\Delta$ that are path-length distance 3 and there exists a unique path $(i, r, s, j)$ of length 3 connecting $i$ and $j$. Then

$$
\theta_{i}-(\beta+1) \theta_{r}+(\beta+1) \theta_{s}-\theta_{j}=0
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## Proof outline part 5

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To show this, expand the right-hand side of

$$
0=\left[A^{*}, A^{* 2} A-\beta A^{*} A A^{*}+A A^{* 2}-\gamma^{*}\left(A A^{*}+A^{*} A\right)-\delta^{*} A\right]
$$

and left and right multiply by $E_{i}$ and $E_{j}$, respectively, and simplify.

## Proof outline part 6

We can now easily show that $\Delta$ is a path by showing that every vertex in $\Delta$ is adjacent to at most two other vertices. Suppose there exists a vertex $i$ in $\Delta$ that is adjacent to at least three other vertices. Without loss of generality, assume that this setup looks like this:

## Proof outline part 6

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$\Delta$

## Proof outline part 7

Given the previously-established algebraic facts,

$$
\theta_{i-2}-(\beta+1) \theta_{i-1}+(\beta+1) \theta_{i}-\theta_{j}=0
$$

and

$$
\theta_{i-2}-(\beta+1) \theta_{i-1}+(\beta+1) \theta_{i}-\theta_{j^{\prime}}=0
$$

Comparing these equations, we find $\theta_{j}=\theta_{j^{\prime}}$. Recall that $\left\{\theta_{h}\right\}_{h=0}^{d}$ are mutually distinct, so $j=j^{\prime}$. This is a contradiction and we have now shown that $\Delta$ is a path.

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The ordering of primitive idempotents $E_{0}, E_{1}, \ldots$ induced by the path is $Q$-polynomial, so the pair $(E, F)=\left(E_{0}, E_{1}\right)$ is $Q$-polynomial.

## Summary

We defined the closely related notions of Leonard pairs and Leonard systems. We then relaxed the definition of a Leonard system by considering a system based on two linear transformations, but which only satisfies half of the properties.

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We also defined a corresponding graph $\Delta$ and what must be true about $\Delta$ for the aforementioned system to be a Leonard system. This led to the definition of the $Q$-polynomial property.

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THE END


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